

Emergent counter-current swimming of Zooplankton

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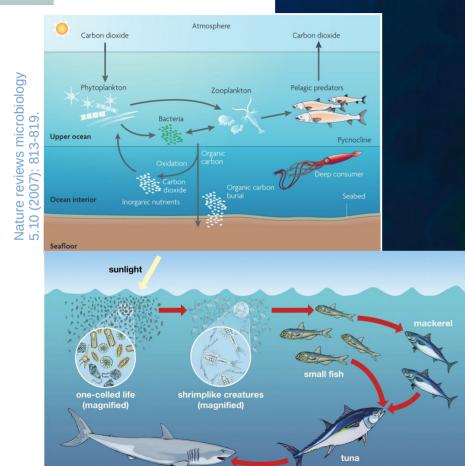


The Nordic Institute for Theoretical Physic

Introduction

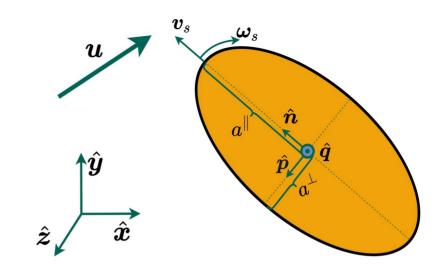
large shark

A phytoplankton bloom seen from space. A bloom triggered by a cyclone in 2019 covered nearly 250,000 square kilometers in the South Pacific Ocean. Credit: Alamy





Model



$$\boldsymbol{v} = \boldsymbol{u}_{\text{flow}}(\boldsymbol{x}, t) + v_{\text{swim}} \hat{\boldsymbol{n}}$$

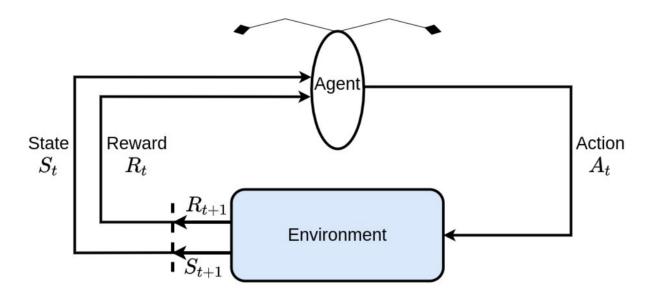
$$\boldsymbol{\omega} = \boldsymbol{\Omega}_{\text{flow}}(\boldsymbol{x}, t) + \boldsymbol{\Lambda} \hat{\boldsymbol{n}} \times \mathbb{S}_{\text{flow}}(\boldsymbol{x}, t) \hat{\boldsymbol{n}} + \boldsymbol{\omega}_{\text{swim}}$$

$$\Lambda = \frac{\lambda^2 - 1}{\lambda^2 + 1}, \quad \lambda = \frac{a^{\parallel}}{a^{\perp}}$$
Active control

Smart Swimmer

Ability to accomplish complex goals

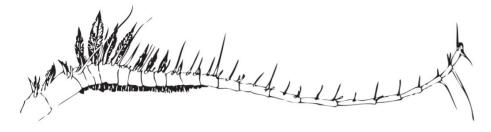
Life 3.0 , Max Tegmark



Reinforcement learning an introduction, R. Sutton and A. Barto.

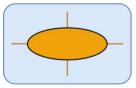
$$Q(s,a) = Q(s,a) + \alpha \left[R + \gamma \max_{a'} Q(s',a') - Q(s,a) \right]$$

Sensing abilities



Small, Wet, and Rational, Andre Visser

Can they distinguish?

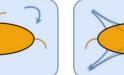


Advection

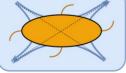


(Translational)





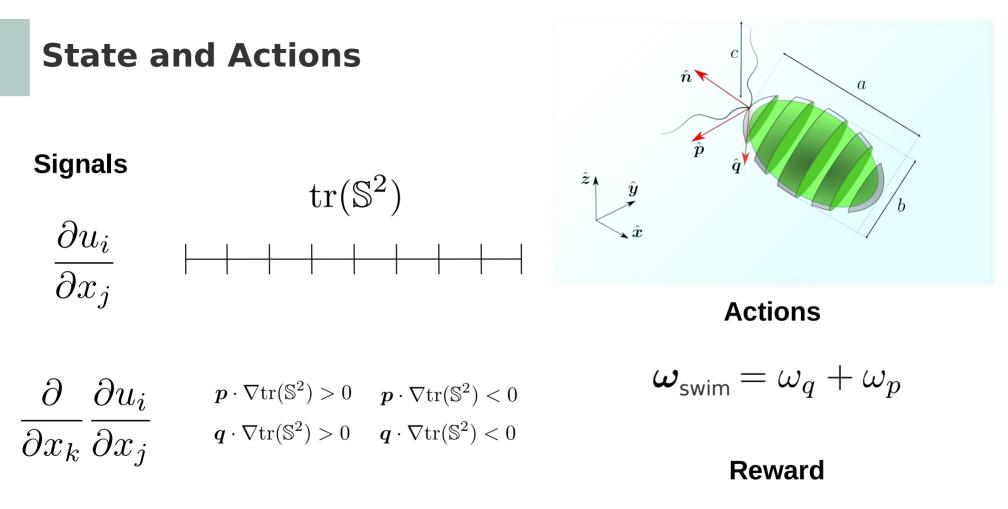
Slip velocity (Angular)



Fluid strain

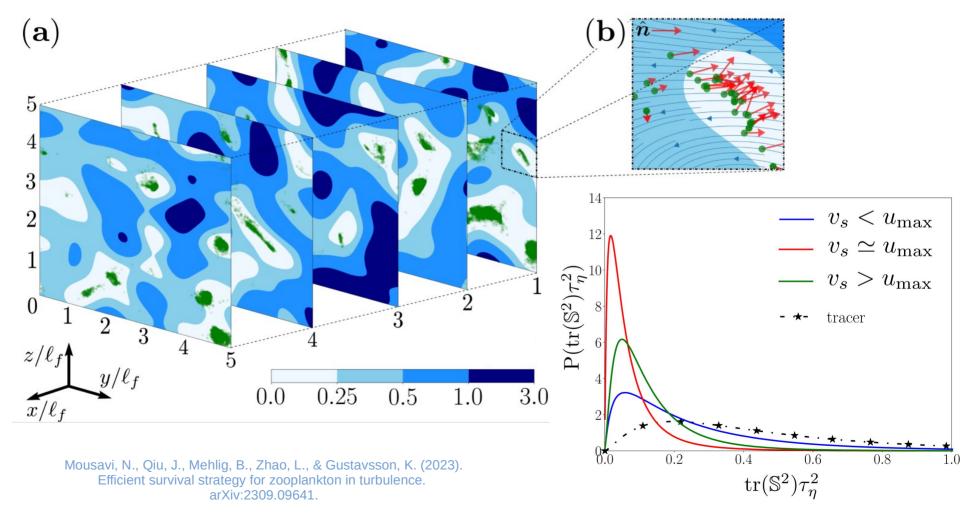
Goal Avoid high strain ?





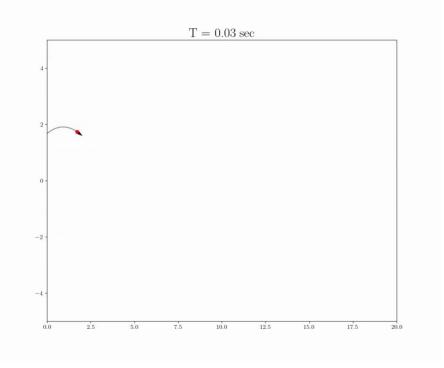
 $R \propto -\mathrm{tr}(\mathbb{S}^2)$

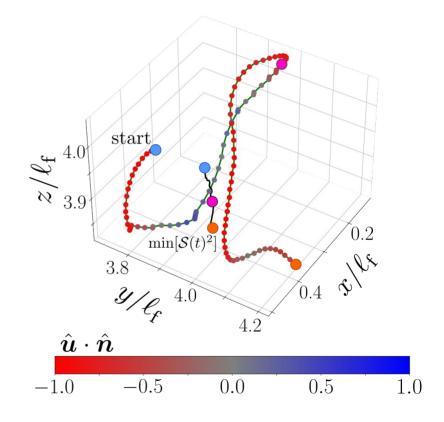
Optimal Navigation



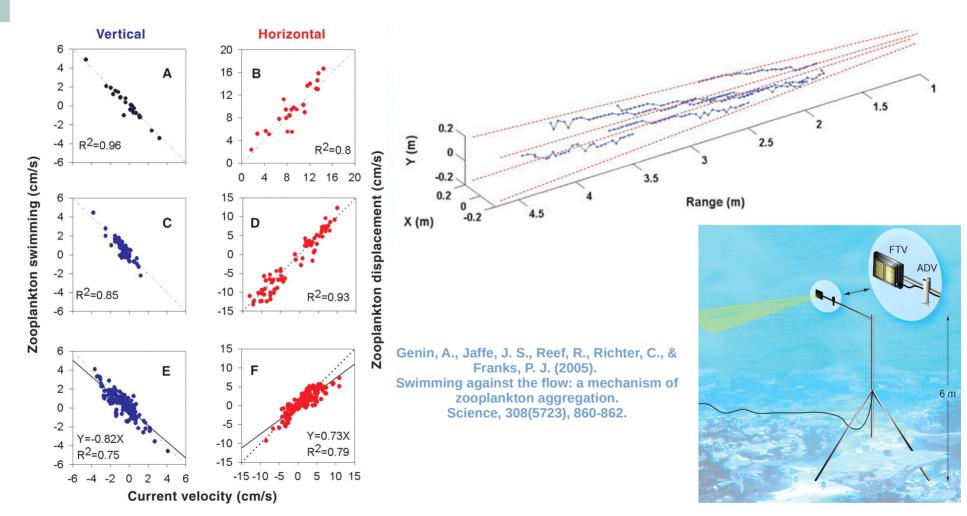
Optimal Navigation

Mousavi, N., Qiu, J., Mehlig, B., Zhao, L., & Gustavsson, K. (2023). Efficient survival strategy for zooplankton in turbulence. arXiv:2309.09641.





Counter-current swimming in nature



Thanks for listening!



